



Virtual Information Exchange: *Moving the Needle on CAV Research: Recent TETC Projects for Connected Vehicles*

November 9, 2023

Welcome

• We are using **Zoom Webinar**

- AUDIO (Computer): Use your computer speakers and microphone by clicking the "Join Audio" button at the bottom left of the screen. You will be muted.
- Alternate Audio (Phone): Call into the meeting by dialing the phone number based on your location (provided in the confirmation email) and enter the Meeting ID at the prompt. You will be muted.
- This web meeting is being recorded.
- Questions with the audio or web? Please contact Esther via email (ekleit@kmjinc.com)





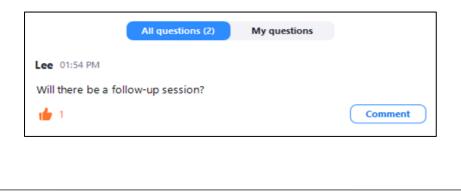


Asking Questions in the Q&A Box

• Click on the Q&A icon at the bottom of your screen



- The questions in the Q&A box will be monitored and answered either between presentations or at the end of the meeting
- You can keep track of your questions in the "My Questions" tab in the Q&A box



Asking Questions Verbally

- Please raise your hand (click on the hand icon at the bottom of the screen), and a host will unmute you.
- Please give your name and agency before asking your question



Please mute yourself when you are finished speaking

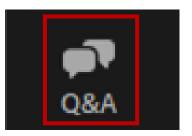




Polling & Discussion Questions

- Please participate in the meeting!
- For any **polling** or **discussion** questions, please feel free to enter additional information or additional thoughts into the Q&A.

If you use the Q&A, please note that **poll #** for reference.





Welcome



Lisa Miller

Innovation Program Associate The Eastern Transportation Coalition



Coalition TSMO Update – Recent & Upcoming Events

RECENT

- ✓ Freight Data and Planning Working Group Web Meeting Sep 13, 2023
- Regional HOGs In-person Exchange with Virtual Reality TIM Training Session (*invite only*) –
 Sept 13, 2023 (New England), Oct 19, 2023 (Potomac) and Nov 2 (Delaware Valley)
- ✓ RITIS User Group Meeting Oct 19, 2023
- Travel Information Summit, Raleigh, NC & via web (invite only) October 24 & 25, 2023

UPCOMING

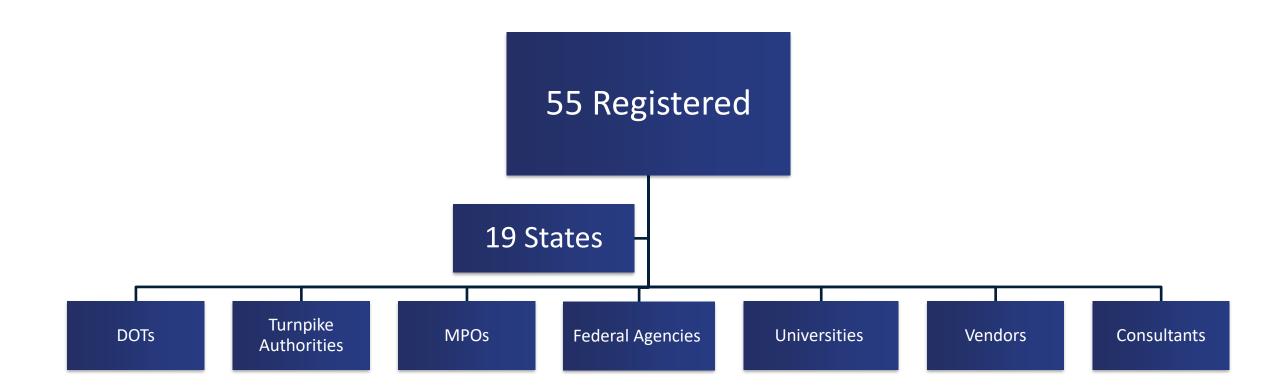
- MBUF International Truck Pilot Report A Scalable Approach that Links Road Use & Payment -Nov 21, 2023
- Southern HOGs In-person Exchanges with Virtual Reality TIM Training Sessions (invite only) -December 6, 2023
- TDM State Point of Contact Meeting (invite only) November 14, 2023
- RITIS Workshop December 5, 2023







The Eastern Transportation Coalition Sponsored Event





Agenda

Торіс	Speaker
Housekeeping	Joanna Reagle, KMJ Consulting, Inc.
Welcome & Update from the Eastern Transportation Coalition Framing the Discussion	Lisa Miller, Innovation Program Associate, The Eastern Transportation Coalition
2023 ADAS Driver Education Pilot Study	Kathleen Rizk, Senior Director, User Experience Benchmarking & Technology, JD Power Lisa Boor, Senior Manager, Auto Benchmarking, JD Power
CTDOT/TETC AV Lane Marking Evaluation Study Report	Peter Calcaterra, Transportation Planner, Connecticut DOT Shaon Mohammed Associate Research Scientist, University of Connecticut Eric Jackson, Executive Director, Connecticut Transportation Institute/ University of Connecticut
Wrap Up	Lisa Miller
November 9, 2023 The Eastern Transportation Coalitio	tetcoalition.org on - Virtual Information Exchange: Moving the Needle on CAV Research 9

Speakers



Kathleen Rizk Senior Director, User Experience Benchmarking & Technology JD Power

Lisa Boor Senior Manager, Auto Benchmarking JD Power



Peter Calcaterra Transportation Supervising Planner, Bureau of Public Transportation Connecticut DOT



Shaon Mohammed Associate Research Scientist University of Connecticut



Eric Jackson Executive Director CT Transportation Institute/ University of Connecticut tetcoalition.org

November 9, 2023

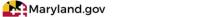
Framing the Discussion



Lisa Miller Innovation Program Associate The Eastern Transportation Coalition



Moving the Needle on CAV Research



Maryland's Connected and Automated Vehicle Program



Home About Maryland CAV Working Group Collaboration with Industry Events, Education, & Resources Contact Us







Poll 1:

What are you learning through CAV readiness work in your state? (open ended question)

• Please submit your answer in the Q&A box.





The Eastern Transportation Coalition - Virtual Information Exchange: Moving the Needle on CAV Research

Why should we get ready?









How does safety fit into the mix?

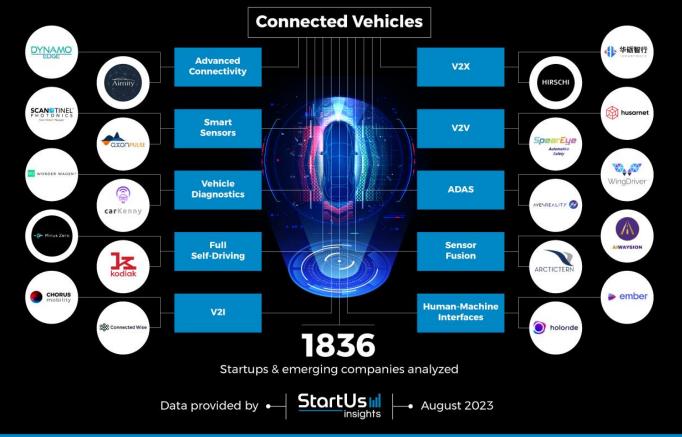


Messaging CAV



Top 10 Connected Vehicle Trends

& Innovations in 2024





Poll 2:

Active Driving Assistance will operate reliably under the following conditions: (*Please select all that apply*)

- When lane paint markings are faded
- At night
- In sharp curves
- When there is snow
- When changing lanes without driver assistance
- None of the above







Welcome to the new TSMO Program Director!



Sheryl Bradley TSMO Program Director The Eastern Transportation Coalition



2023 ADAS Driver Education Pilot Study



Kathleen Rizk, Senior Director, User Experience Benchmarking and Technology JD Power



Lisa Boor, Senior Manager, Auto Benchmarking JD Power



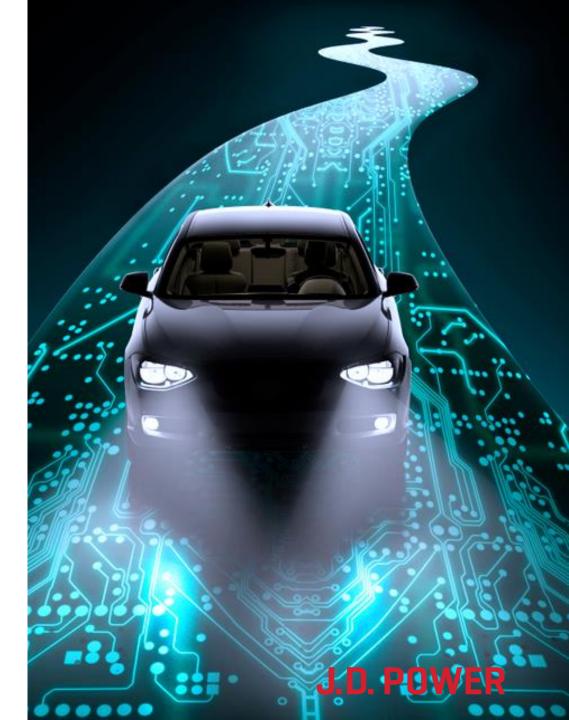
2023 ADAS Driver Education Pilot Study

Findings Presentation

November 9, 2023



THE EASTERN TRANSPORTATION COALITION STUDY FINDINGS | JULY 2023



J.D. POWER



INTRODUCTION

Background

The Eastern Transportation Coalition (TETC), which is comprised of associated State Departments of Transportations (DOTs), is trying to determine how best to ensure that drivers who have more complex Active Driver Assistance Systems (ADAS) technologies on their vehicle, such as Active Driving Assistance, have been properly trained on how to use the technologies including their limitations. This level of knowledge is critical for road safety.

J.D. Power represents the Voice of the Customer (VoC) and with its vast databases is able to determine which ADAS technologies and brands are particularly problematic for users and, what specifically about those technologies makes them difficult to use/understand. J.D. Power can use this knowledge to create a proper training video to ensure that it covers areas where users have difficulties in understanding.

With that in mind, TETC commissioned J.D. Power to conduct the 2023 ADAS Driver Education Pilot Study.

Objectives

The primary objective of the study is to determine if dedicated training on a ADAS technology that is considered complex could elevate user knowledge, and thus, increase proper usage and improve road safety. Secondary objectives include:

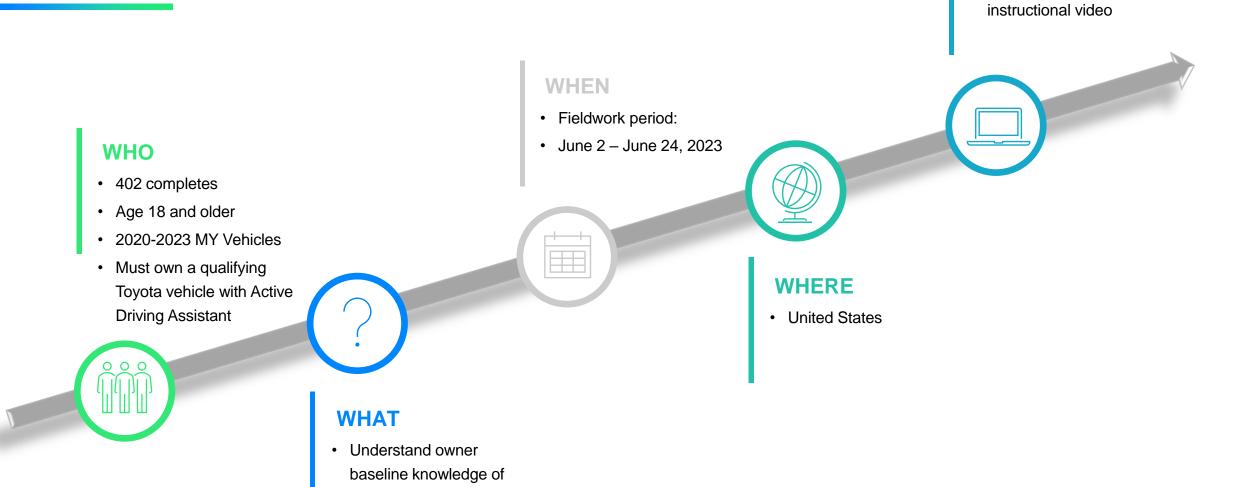
- Understand consumers' perception regarding perceived ease of use of the technology and any items that they considered to be difficult to use/understand
- Measure consumers' baseline knowledge about a technology before completing the training among those with the feature on their vehicle
- Utilize J.D. Power's knowledge of the VoC from its extensive databases to build a 7-minute training video that takes into consideration factors where owners struggle (e.g., limitations, feature reaction, understanding status images in the instrument cluster) as the basis for the training
- Measure consumers' knowledge about the technology after completing the training to determine the effectiveness of proper training
- Conduct a review of the training process, as well as determine where training content needs to be enhanced to further address
 gaps in user knowledge
- Identify how best to train consumers on ADAS technologies (e.g., in-person, self-administered) based on their learning preferences

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METHODOLOGY

Methodology



their Active Driving Assistant feature and impact on knowledge with proper training

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HOW

• Online survey with

Why Toyota's Active Driving Assistance Technology was Selected

Technology and Brand Selection Consideration Factors

ADAS Technology Consideration Factors:

- Level of user interaction: active vs. passive engagement
- Technology penetration
- J.D. Power quality metrics (Problems Per 100)
- Feature complexity

Brand Consideration Factors:

- Mass Market vs. Premium brand
- Diverse product portfolio across vehicle segments
- J.D. Power quality metrics (Problems Per 100)
- Brand demographics

Toyota Active Driving Assistance

- Active feature
- Higher-level technology requiring multiple features to be active. This feature is the simultaneous use of lane centering assistance and adaptive cruise control. The driver must supervise and support the feature and maintain responsibility for driving
- Toyota is one of the most problematic brands*
- Toyota is a Mass Market brand with a diverse product portfolio

^{* 2022} TXI data based on ACC and LKA; 2023 TXI based on ACC and Lane Centering © 2023 J.D. Power. All Rights Reserved. CONFIDENTIAL & PROPRIETARY

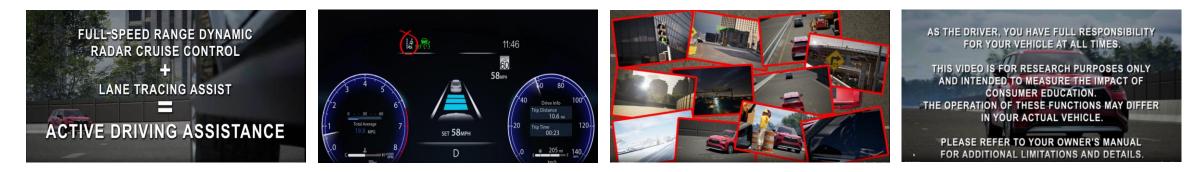
Toyota Active Driving Assistance Training Video Content

J.D. Power developed a seven-minute video that provided a high-level overview of the technology as well as the specifics of the feature for the Toyota brand.

The video content was highly driven by J.D. Power quality metrics and VoC expertise to highlight the areas customers need to know to improve their experience with the feature.

Video content includes:

- Explanation of the feature settings
- How to engage/disengage the feature, including when the system is in a "ready" state vs. an "active" state
- The requirements to operate the feature (e.g., minimum speed)
- The feature's reaction under various conditions (e.g., lane markings no longer visible)
- The feature's limitations (i.e., on curves)
- The meaning of the feature's display images, icons, warnings and alerts messaging



https://txi3danimations.s3.amazonaws.com/FULL_Version07.mp4

Note: The questions in this study were not designed to mislead the respondent but rather focused on critical information needed to use the feature properly and safely. © 2023 J.D. Power. All Rights Reserved. CONFIDENTIAL & PROPRIETARY

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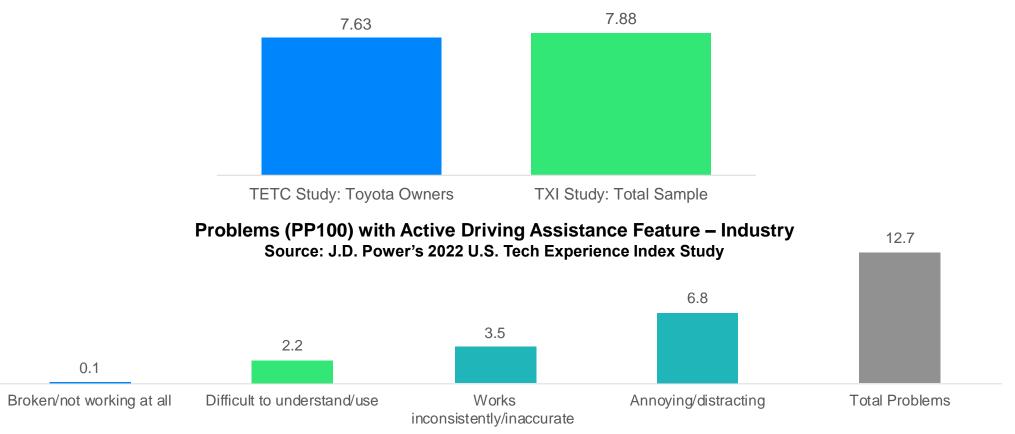


KEY FINDINGS

KEY FINDING

1. While the TETC study focused on Toyota owners of the Active Driving Assistance, most of the findings can be applied across the automotive industry, regardless of brand, and are not only specific to Toyota (1 of 2)

The findings for the Active Driving Assistance feature, in J.D. Power's 2022 Tech Experience Index Study (TXI) are similar to the findings in the TETC Pilot Study that focuses on Toyota's system.

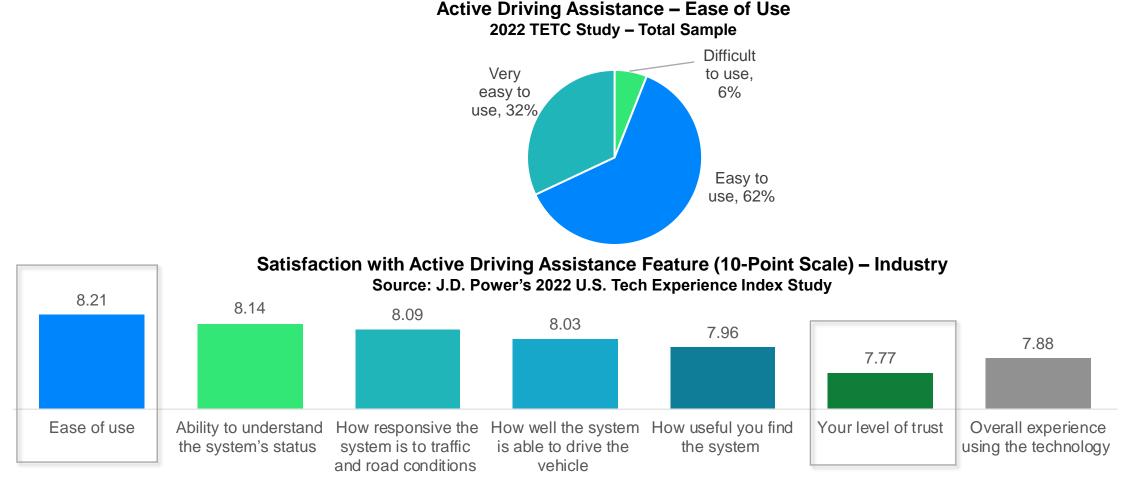


Overall Satisfaction with Active Driving Assistance Feature (10-Point Scale) – Total Sample

© 2023 J.D. Power. All Rights Reserved. CONFIDENTIAL & PROPRIETARY © 2023 J.D. Power. All Rights Reserved. CONFIDENTIAL & PROPRIETARY KEY FINDING

1. While the TETC study focused on Toyota owners of the Active Driving Assistance, most of the findings can be applied across the automotive industry, regardless of brand, and are not only specific to Toyota (2 of 2)

All brands have various issues with their execution of this technology as seen when comparing the findings from the TETC study to the TXI study.

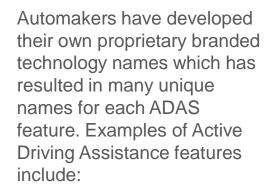


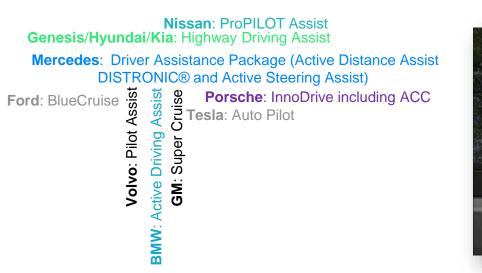
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2. Like other OEMs, Toyota's naming conventions impacted consumer understanding of Active Driving Assistance

Standardized naming conventions and definitions for Active Driving Assistance features are needed to improve consumer understanding. For example, Toyota uses complex naming conventions for their Active Driving Assistance technology:

- Adaptive Cruise Control (ACC) is called Full-Speed Range Dynamic Radar Cruise Control, which is a tongue-twister
- Lane Centering is called Lane Tracing Assist, and comprised of three levels of lane support (i.e., Lane Departure Warning, Lane Keeping Assist, and Lane Centering)
- To further complicate, the Active Driving Assistance feature is packaged with other ADAS features in what Toyota markets as Safety Sense[™]

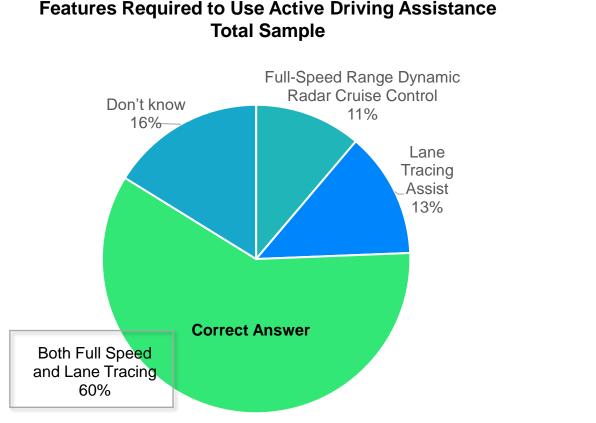




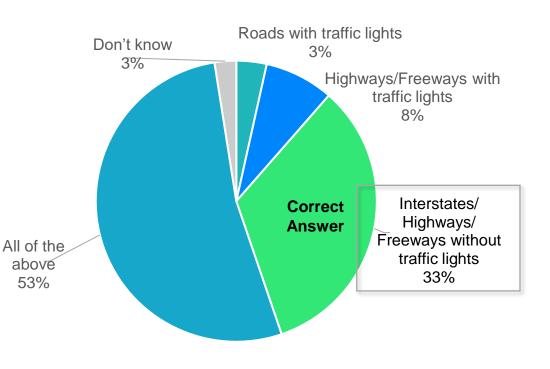


3. Lack of critical knowledge regarding the Active Driving Assistance feature introduces risk

Even fundamental questions about Active Driving Assistance are not known by many of the owners, which is very concerning.



Type of Road Where Feature Works Properly Total Sample



KEY FINDING

4. Pre-assessment reveals consumer knowledge about the Active Driving Assistance feature is almost non-existent

The average accuracy rate across the tested metrics was 34% before the training, which is very concerning.

Pre-Video	
Scorecard	

Best	
Worst	
Worst	

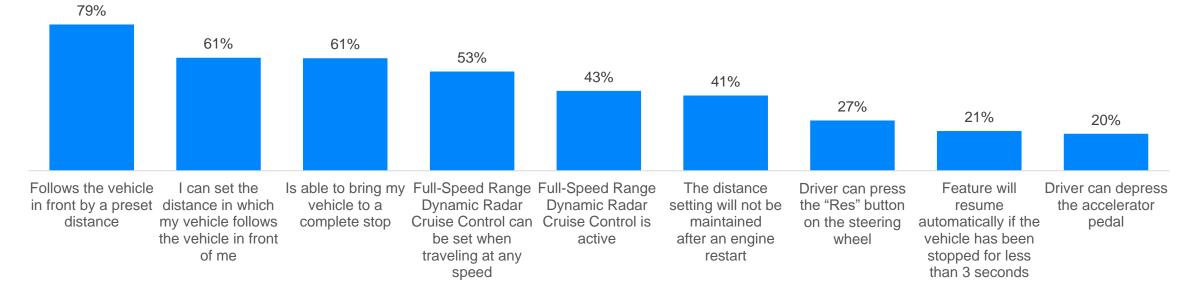
		Total Sample
Limitations	Follows the vehicle in front by a preset distance	79%
Instrument Cluster Image 1 (ADA)	Active Driving Assistance is Activated (Image 2)	61%
Settings	I can set the distance in which my vehicle follows the vehicle in front of me	61%
Limitations	Is able to bring my vehicle to a complete stop	61%
Equipment Needed	Both Full Speed and Lane Tracing	59%
Limitations	Cannot change lanes automatically without driver assistance	59%
Limitations	Isn't able to navigate around potholes	55%
Feature Reaction: No Turn Signal	Resists the lane change	54%
Settings	Full-Speed Range Dynamic Radar Cruise Control can be set when traveling at any speed	53%
Instrument Cluster Image 2 (Departing Lane on Right)	Vehicle is inadvertently exiting the lane on the right	49%
Instrument Cluster Image 3 (LKA on right only)	Full-Speed Range Dynamic Radar Cruise Control is active	45%
Speed Requirement	At 32 MPH or above	44%
Instrument Cluster Image 2 (Departing Lane on Right)	Full-Speed Range Dynamic Radar Cruise Control is active	43%
Settings	The Lane Tracing Assist stays on after an engine restart	43%
Settings	The distance setting will not be maintained after an engine restart	41%
Feature Reaction: Hands Off Wheel	Provides a visual warning "Hold Steering Wheel" in Driver Support Screen	39%
Road Type	Interstates/Highways/Freeways without traffic lights	33%
Instrument Cluster Image 3 (LKA on right only)	Vehicle is receiving steering support for the right side of the lane	32%
Feature Reaction: Resume Driving	Driver can press the "Res" button on the steering wheel	27%
Limitations	Cannot detect pedestrians	24%
Instrument Cluster Image 3 (LKA on right only)	Active Driving Assistance is in standby mode	24%
Feature Reaction: Hands Off Wheel	Beeps	24%
Feature Reaction: No Lane Markings	One or both blue lines no longer appear in the Driver Support screen	23%
Feature Reaction: No Lane Markings	Beeps	23%
Feature Reaction: Resume Driving	Feature will resume automatically if the vehicle has been stopped for less than 3 seconds	21%
Feature Reaction: No Lane Markings	All options (One or both blue lines no longer appear in the Driver Support screen, Beeps, Will no longer keep the vehicle centered in the lane, Goes into standby mode)	21%
Limitations	Does not operate reliably when lane paint is faded	21%
Instrument Cluster Image 2 (Departing Lane on Right)	Vehicle is receiving steering support for the left side of the lane	20%
Feature Reaction: Resume Driving	Driver can depress the accelerator pedal	20%
Limitations	Does not operate reliably in sharp curves	19%
Limitations	Does not operate reliably when there is snow	19%
Limitations	Does not operate reliably when there are gaps in the lane markings for freeway exits/entrances	17%
Feature Reaction: Hands Off Wheel	After issuing one or multiple warnings, the feature will go into standby mode	16%
Feature Reaction: No Lane Markings	Will no longer keep the vehicle centered in the lane	15%
Settings	I can't change the volume of the audible warnings	14%
Feature Reaction: No Lane Markings	Goes into standby mode	12%
Limitations	Does not operate reliably at night	8%
	Average Score 12 Questions	35%
	Average Score 11 Questions	34%

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33

5. There is a better understanding of the Adaptive Cruise Control component of the Active Driving Assistance feature than Lane Centering before the training (1 of 2)

The Adaptive Cruise Control (Toyota's Full-Speed Range Dynamic Radar Cruise Control) portion of the Active Driving Assistance feature is both less complex to operate and has been around for many years so numerous owners have prior experience with it. Even so, their knowledge is deficient in terms of knowing the details.



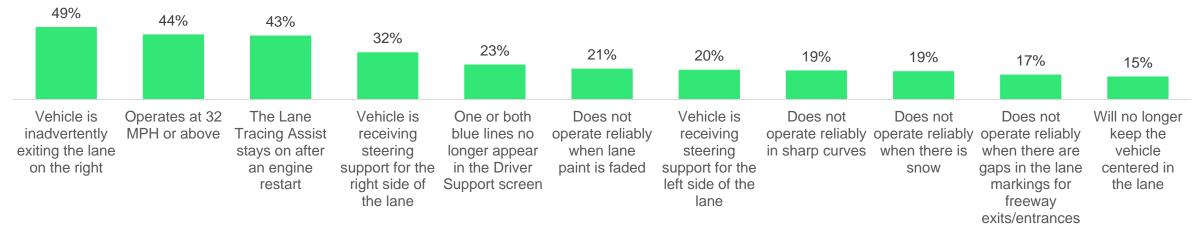
Adaptive Cruise Control (Full-Speed Range Dynamic Radar Cruise Control) – Percent Correct Total Sample

KEY FINDING

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5. There is a better understanding of the Adaptive Cruise Control component of the Active Driving Assistance feature than Lane Centering before the training (2 of 2)

Owners have difficulty understanding the Lane Centering (Toyota's Lane Tracing Assist) feature and Knowledge further declines when the user needs to understand how the two features operate together to get Active Driving Assistance.



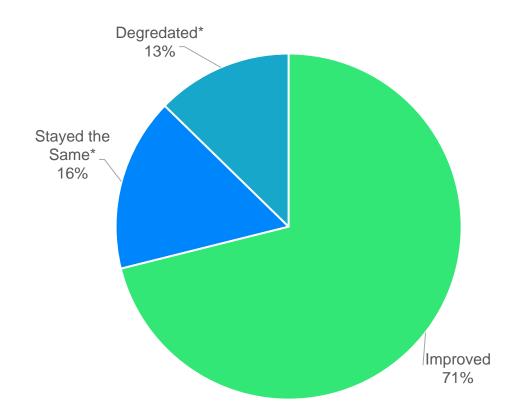
Lane Centering (Lane Tracing Assist) – Percent Correct Total Sample

KEY FINDING

KEY FINDING

6. Participants positively benefited from the video training with the majority of respondents making learning improvements

The respondents' education, income, and location were not differentiators of learning improvements. The impact of training was highest among older respondents with higher levels of improved learning.



Impact of Video Training - Total Sample



7. Almost every metric showed improvement from the training video, but the status images and feature reaction to missing lane markings are still difficult for owners to understand

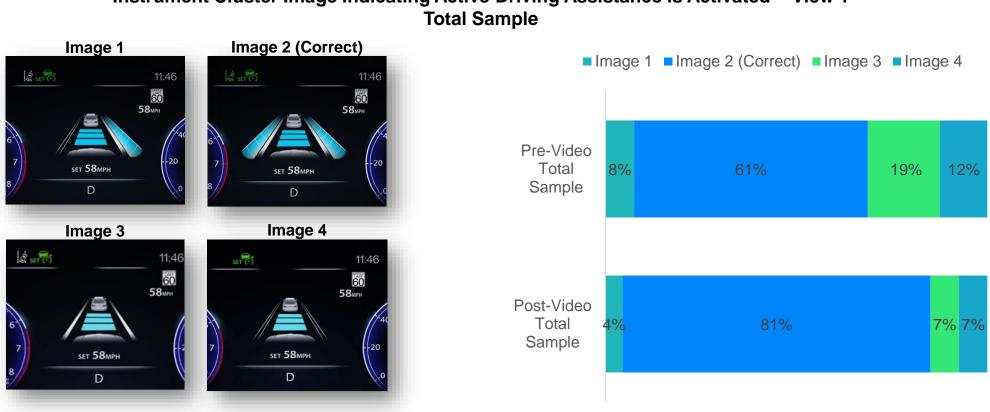
Post Video Scorecard

KEY FINDING

		Total Sample: Pre-Training	Total Sample: Post-Training	Better/(Worse
Equipment Needed	Both Full Speed and Lane Tracing	59%	N/A	N/A
Limitations	Follows the vehicle in front by a preset distance	79%	93%	14
Settings	I can set the distance in which my vehicle follows the vehicle in front of me	61%	87%	26
Limitations	Is able to bring my vehicle to a complete stop	61%	85%	24
instrument Cluster Image 1 (ADA)	Active Driving Assistance is Activated (Image 2)	61%	81%	20
Limitations	Cannot change lanes automatically without driver assistance	59%	79%	20
Limitations	Does not operate reliably when lane paint is faded	21%	78%	57
Limitations	Isn't able to navigate around potholes	55%	77%	22
ipeed Requirement	At 32 MPH or above	44%	73%	29
Feature Reaction: Hands Off Wheel	Provides a visual warning "Hold Steering Wheel" in Driver Support Screen	39%	73%	34
Limitations	Does not operate reliably when there is snow	19%	71%	52
Feature Reaction: No Turn Signal	Resists the lane change	54%	70%	16
Road Type	Interstates/Highways/Freeways without traffic lights	33%	69%	36
limitations	Does not operate reliably when there are gaps in the lane markings for freeway exits/entrances	17%	69%	52
Limitations	Does not operate reliably in sharp curves	19%	66%	47
limitations	Cannot detect pedestrians	24%	65%	41
Feature Reaction: Resume Driving	Feature will resume automatically if the vehicle has been stopped for less than 3 seconds	21%	61%	40
Settings	I can't change the volume of the audible warnings	14%	60%	46
Settings	Full-Speed Range Dynamic Radar Cruise Control can be set when traveling at any speed	53%	58%	5
Limitations	Does not operate reliably at night	8%	57%	(49)
Feature Reaction: Resume Driving	Driver can press the "Res" button on the steering wheel	27%	56%	29
ettings	The Lane Tracing Assist stays on after an engine restart	43%	53%	10
ettings	The distance setting will not be maintained after an engine restart	41%	53%	12
nstrument Cluster Image 3 (LKA on right only)	Full-Speed Range Dynamic Radar Cruise Control is active	45%	50%	5
Feature Reaction: Hands Off Wheel	Beeps	24%	50%	26
instrument Cluster Image 2 (Departing Lane on Right)	Vehicle is inadvertently exiting the lane on the right	49%	47%	(2)
instrument Cluster Image 2 (Departing Lane on Right)	Full-Speed Range Dynamic Radar Cruise Control is active	43%	46%	3
instrument Cluster Image 2 (Departing cane on right)	Active Driving Assistance is in standby mode	24%	46%	22
instrument Cluster Image 3 (LKA on right only)	Vehicle is receiving steering support for the right side of the lane	32%	45%	13
Feature Reaction: Hands Off Wheel	After issuing one or multiple warnings, the feature will go into standby mode	16%	44%	28
Feature Reaction: Resume Driving	Driver can depress the accelerator pedal	20%	38%	18
Feature Reaction: No Lane Markings	All of the above (One or both blue lines no longer appear in the Driver Support screen, Beeps, Will	2070	20,0	10
	no longer keep the vehicle centered in the lane, Goes into standby mode)	21%	34%	13
eature Reaction: No Lane Markings	One or both blue lines no longer appear in the Driver Support screen	23%	32%	9
instrument Cluster Image 2 (Departing Lane on Right)	Vehicle is receiving steering support for the left side of the lane	20%	32%	12
Feature Reaction: No Lane Markings	Goes into standby mode	12%	30%	18
Feature Reaction: No Lane Markings	Will no longer keep the vehicle centered in the lane	15%	24%	9
Feature Reaction: No Lane Markings	Beeps	23%	17%	(6)
	Average Score 12 Questions	35%	N/A	N/A
	Average Score 11 Questions	34%	57%	23

8. Active Driving Assistance status images displayed in the instrument cluster are not understood, which is concerning (1 of 3)

Before training, almost 40% of owners didn't know the basic meaning of the image displayed in the instrument cluster showing the status of Active Driving Assistance. It is alarming that this large share of the user base cannot identify the status of the feature from the image provided.



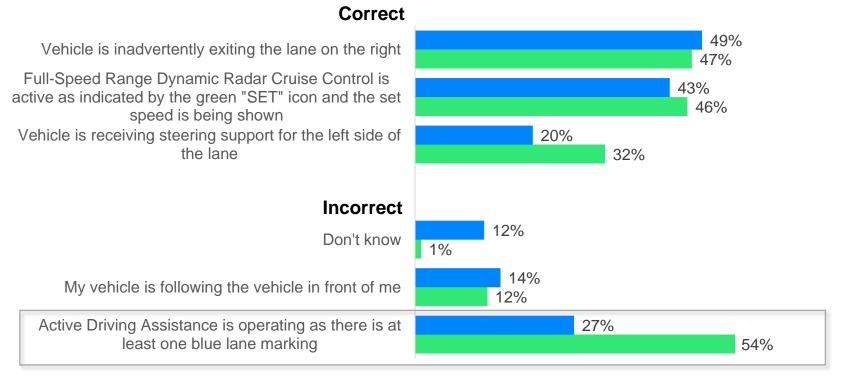
Instrument Cluster Image Indicating Active Driving Assistance is Activated – View 1

8. Active Driving Assistance status images displayed in the instrument cluster are not understood, which is concerning (2 of 3)

Understanding the instrument cluster images remains a challenge with more respondents making incorrect selections post-video.







Pre-Video

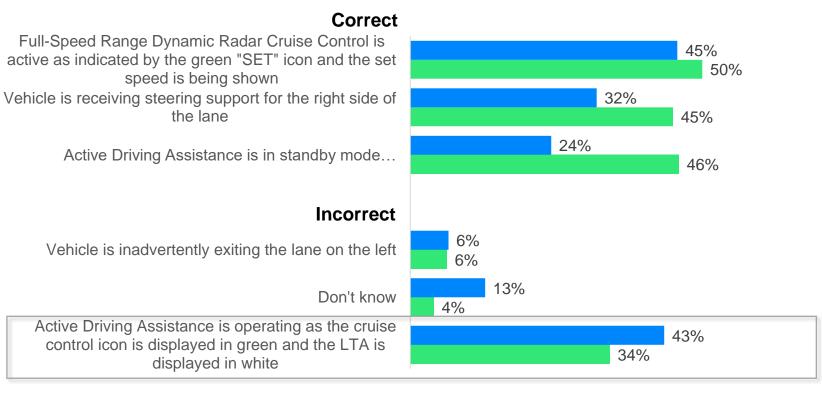
Post-Video

8. Active Driving Assistance status images displayed in the instrument cluster are not understood, which is concerning (3 of 3)

Difficulty deciphering between the Active Driving Assistance and the Adaptive Cruise Control instrument cluster images remain and result with one-third of owners incorrectly thinking the feature is active post-training.

Instrument Cluster Active Driving Assistance Status Image Indication – View 3 Total Sample





Post-Video

9. Feature reactions and limitations are not known by the majority of owners, which has the potential to create risky situations on the road (1 of 2)

Adding to the urgency of needing to be educated on this technology is the clear lack of understanding the feature's reactions and limitations. Even after watching the video, feature reaction deficiencies persist among those who use the feature.

Feature Reaction	Correct Answer	Total Sample: Pre-Training	Total Sample: Post-Training
No Turn Signal	Resists the lane change	54%	70%
No Lane Markings	All of the above (See "memo" list below)	21%	34%
	Memo: One or both blue lines no longer appear in the Driver Support screen	23%	32%
	Memo: Beeps	23%	17%
	Memo: Will no longer keep the vehicle centered in the lane	15%	24%
	Memo: Goes into standby mode	12%	30%
Hands Off Wheel	Provides a visual warning "Hold Steering Wheel" in Driver Support Screen	39%	73%
	Beeps	24%	50%
	After issuing one or multiple warnings, the feature will go into standby mode	16%	44%
Resume Driving	Driver can press the "Res" button on the steering wheel	27%	56%
	Feature will resume automatically if the vehicle has been stopped for less than 3 seconds	21%	61%
	Driver can depress the accelerator pedal	20%	38%

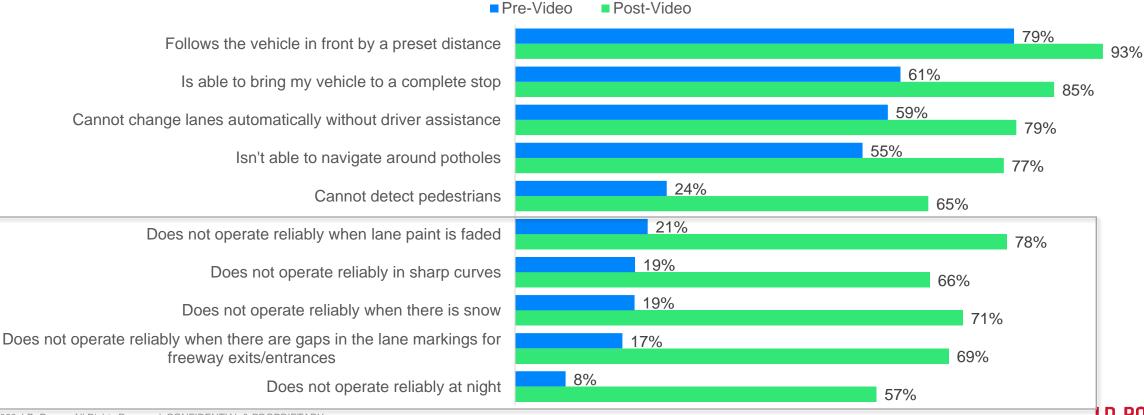
Features Reaction – Percent Correct

Total Sample

9. Feature reactions and limitations are not known by the majority of owners, which has the potential to create risky situations on the road (2 of 2)

Adding to this concern is the fact that owners don't understand the limitations of the feature including some that could introduce risk.

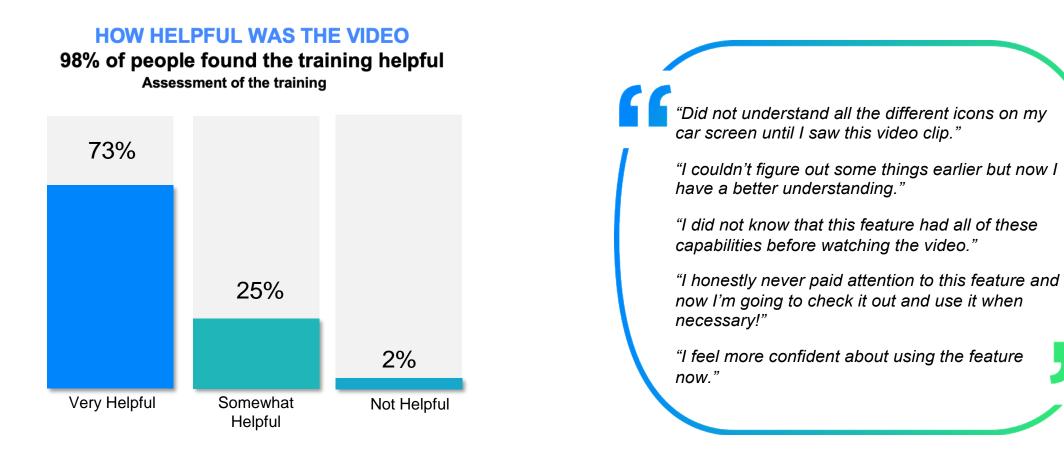
Active Driving Assistance Technology Limitations – Total Sample Percent Correct



KEY FINDING

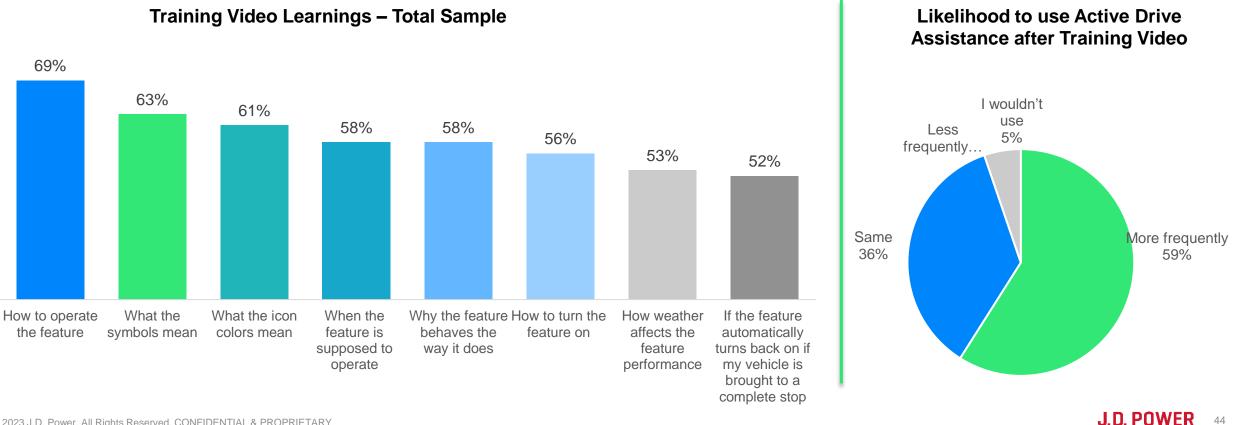
10. Toyota owners found the video training to be helpful and are more likely to use the Active Driving Assistance feature more often and hopefully, use it properly (1 of 2)

Upon completion of the research exercise, respondents were asked to assess the training video. Almost all of Toyota owners found the training helpful.



10. Toyota owners found the video training to be helpful and are more likely to use the Active Driving Assistance feature more often and hopefully, use it properly (2 of 2)

The training elevated the user's understanding across a variety of metrics. The training video increases likelihood for more frequent use; over forty percent of those that don't use it currently indicate they will use it frequently after the training.

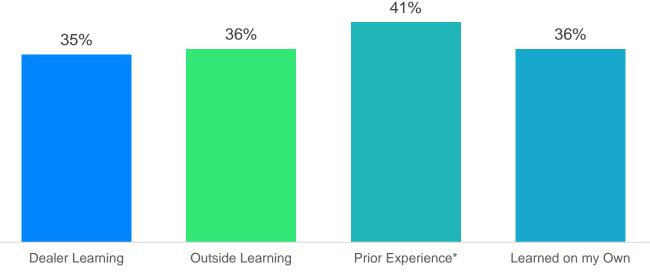


11. Content and depth play a critical role in effectively educating consumers and dealers on the Active Driving Assistance feature

Minimal differences appear in the comparison of the degree of knowledge about the feature by how the owner learned about it, indicating that the educational content being provided is not sufficient for complete user understanding.

Collaboration across the auto industry, dealers, insurance, and state DOTs would transform the industry and consumer education.

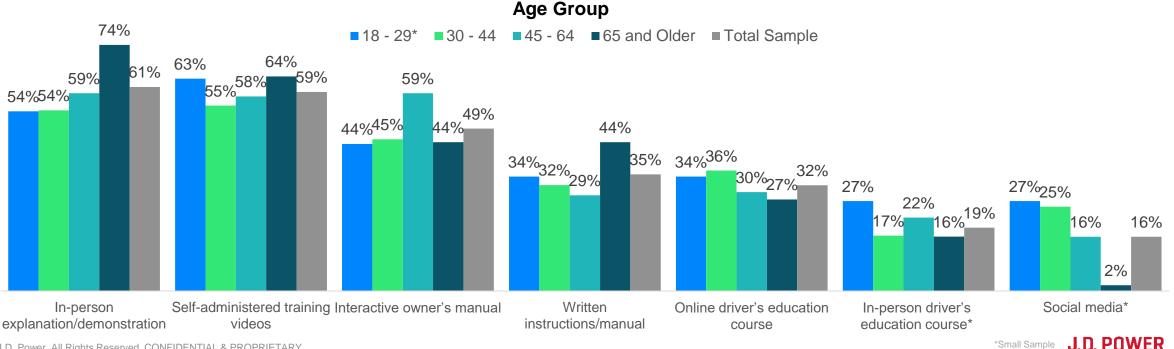
Average % Correct: Pre-Video Total Sample By How Learned



12. An opportunity exists for in-person training or self-administered training videos

Owners express the desire to learn about new technologies through a variety of methods and prefer inperson explanations/demonstrations or self-administered training videos. Owners expect to be educated about new technologies through their dealer or vehicle manufacturer. However, these methods have not been effective.

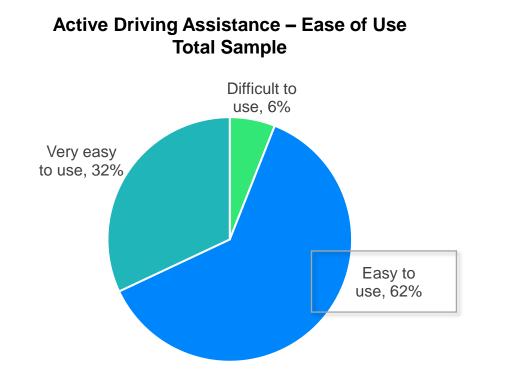
Those who had difficultly learning from the video training are more likely to look to the DOT or an Insurance Provider to educate them and are more open to formal education learning methods.

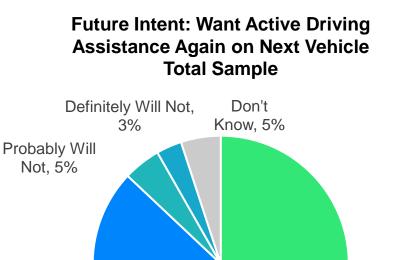


Preferred Method of Learning New Technologies

13. Mandatory educational training may be necessary to elevate the knowledge-base of the Active Driving Assistance feature, which is clearly needed to reduce risk (1 of 2)

With almost 90% of owners wanting this feature again and prior experience having a limited impact on knowledge, requiring training may be the best path forward to ensure proper use of the Active Driving Assistance technology.

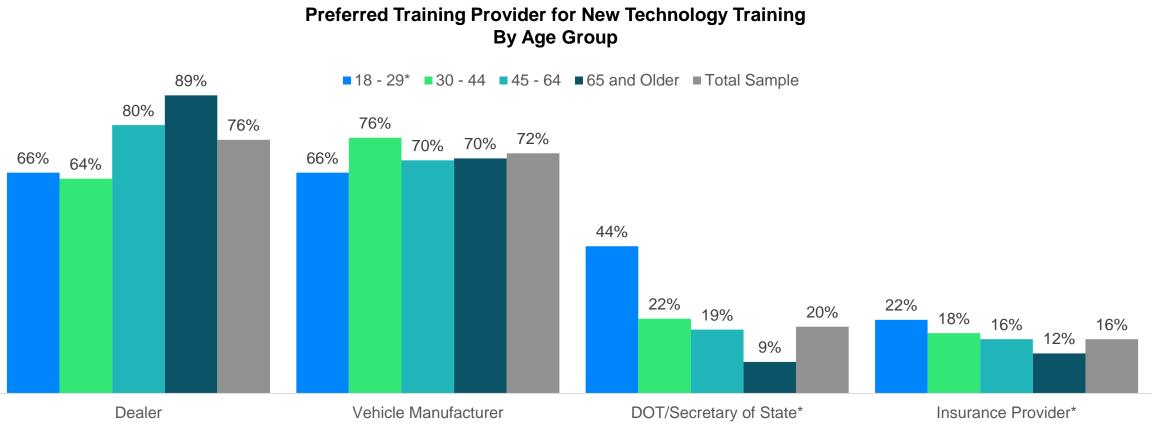




Probably Will, 32% **Definitely** Will, 55%

13. Mandatory educational training may be necessary to elevate the knowledge-base of the Active Driving Assistance feature, which is clearly needed to reduce risk (2 of 2)

If not mandatory, then a variety of training methods need to be offered to meet varying needs of consumers by age and gender. Perhaps, some reward-type system (e.g., insurance discount, subscription service discount) could also be used to encourage training.



KEY FINDING

J.D. POWER

*Small Sar

J.D. POWER



RECOMMENDATIONS

Recommendations

Collaborative Training Content

OEMs must provide critical content to operate their ADAS technologies and elevate driver knowledge of activation, current state, understanding status images, feature reactions, limitations, and settings

3

Increase Variety of Training Methods

There is an opportunity for industry and government stakeholders to create learning methods that leverage consumer preferences for in-person and self-administered learning experiences

2

Increase Training for Dealer Staff

Must ensure dealers are properly trained on complex ADAS features. Leverage the existing dealer relationship to serve as qualified sources for critical information and conduits for proven learning sources

4

DOT Mandated Education

Initial efforts can focus on new and more complex ADAS features. Mandating training ensures all consumers are trained – especially those who overestimate their knowledge. Prior feature experience does not remove the need for training

Contact

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Lisa Boor

Senior Manager, Auto Benchmarking

Lisa.Boor@jdpa.com



CTDOT/TETC AV Lane Marking Evaluation Study Report



Peter Calcaterra, Transportation Supervising Planner, Bureau of Public Transportation Connecticut DOT



Eric Jackson, Executive Director CT Transportation Institute University of Connecticut



Shaon Mohammed,

Associate Research Scientist University of Connecticut



tetcoalition.org

Advanced Driver Assistance Systems (ADAS) Pavement Marking Evaluation in Connecticut

Peter Calcaterra











New Proposed Federal MUTCD Requirements

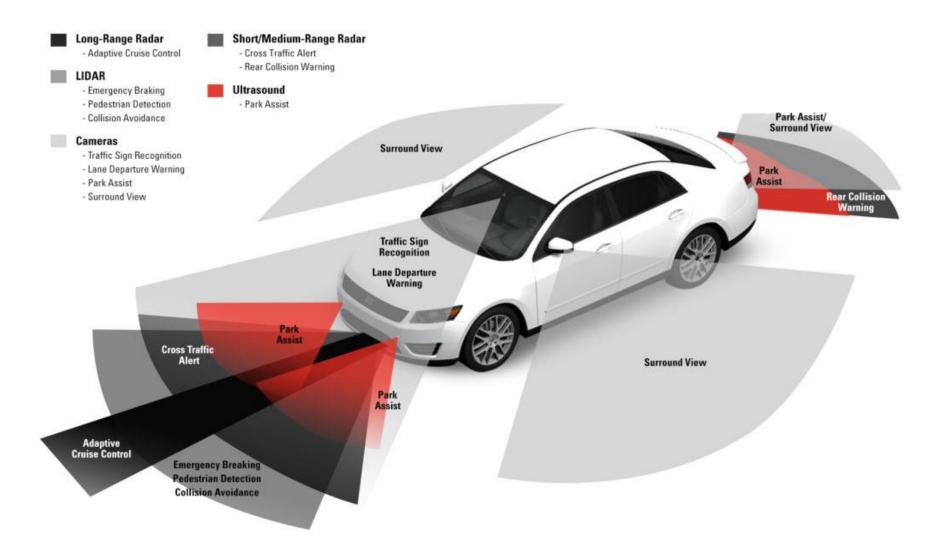
Est. November 7, 1935

Manual on Uniform Traffic Control Devices for Streets and Highways



- 6" wide longitudinal markings on all roads 40+ mph
- 6" wide edge lines on all other roads
- 6" dotted edge line extensions along all entrance and exit ramps, all auxiliary lanes, and all tapers where a deceleration or auxiliary lane is added
- 50 mcd/m2/lx under dry conditions for longitudinal markings on roadways with speed limits of 35+ mph
- Chevron markings in the neutral areas of exit gores to distinguish them from travel lanes.
- Continuous markings at the beginning of work zones and in all lane transitions
- Raised pavement markers only as a supplement to, rather than as a substitute for, markings
- Uniform contrast markings on light-colored pavements to create greater contrast
- Broken lines of at least 10ft in length with a max gap of 30ft.
- Avoidance of decorative elements in crosswalks.

Increasing Percentage of New Cars Sold with ADAS

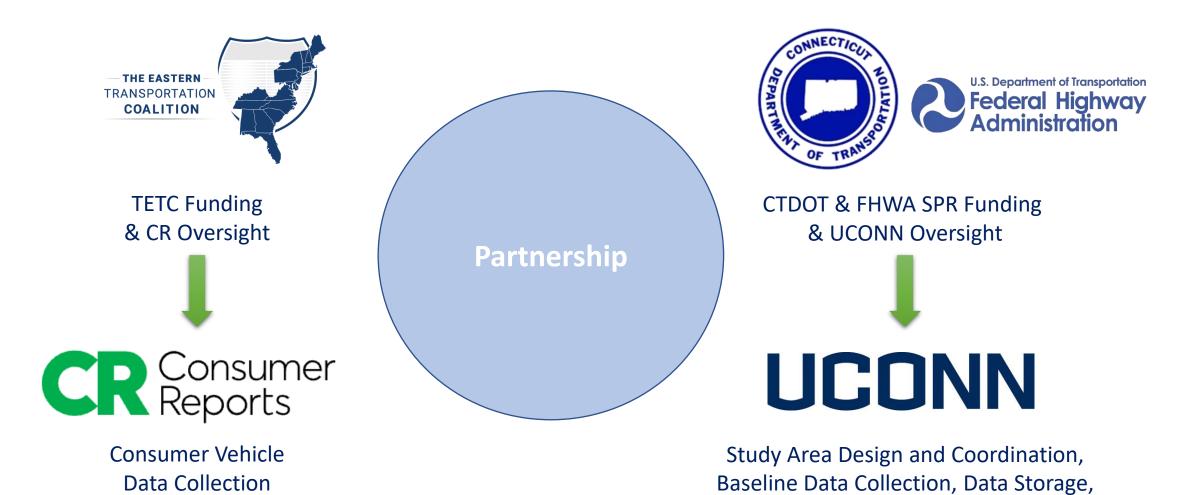


What Pavement Markings & Characteristics Matter for ADAS?

- Width
- Retroreflectivity
- Color
- Markings Age / Condition
- Type
- Paint Type or Material
- Contrast
- Recessed or Surface Applied
- Weather Conditions
- Geometry
- Topography
- Lighting & Time of Day
- Traffic Volume and Speeds



Research Opportunity!



57

Data Analysis, and Reporting

Advanced Driver Assistance Systems (ADAS) Pavement Marking Evaluation in Connecticut

Connecticut Transportation Safety Research Center University of Connecticut





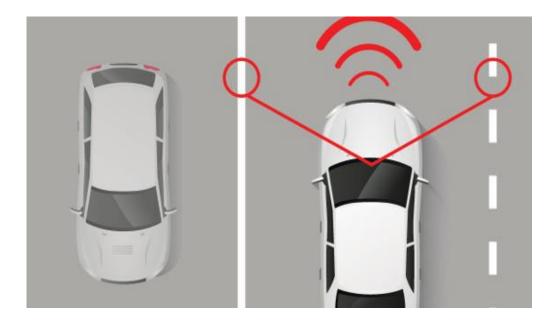






Motivation

- Manufacturers have begun incorporating new ADAS in their vehicles to improve vehicle safety
- Longitudinal pavement markings are the primary roadway asset that ADAS sensors look to for reference

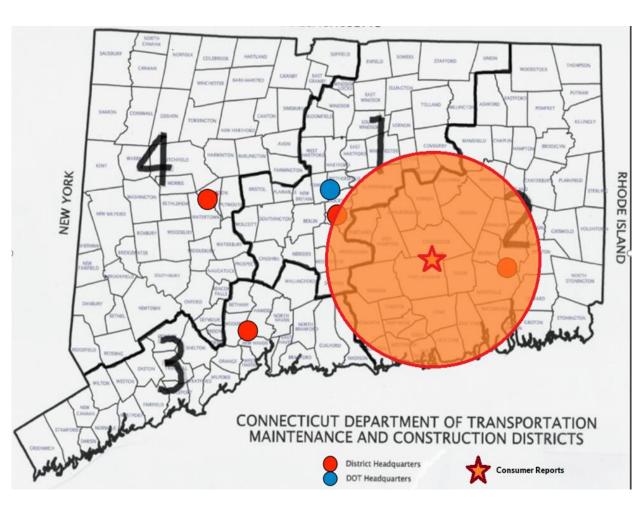


- Can we rely on the existing roadway markings to guide the new cars of today as well as the cars of the future?
- What are the minimum longitudinal marking requirements for driver assistance technologies to be successful in improving roadway performance and safety?

Objectives

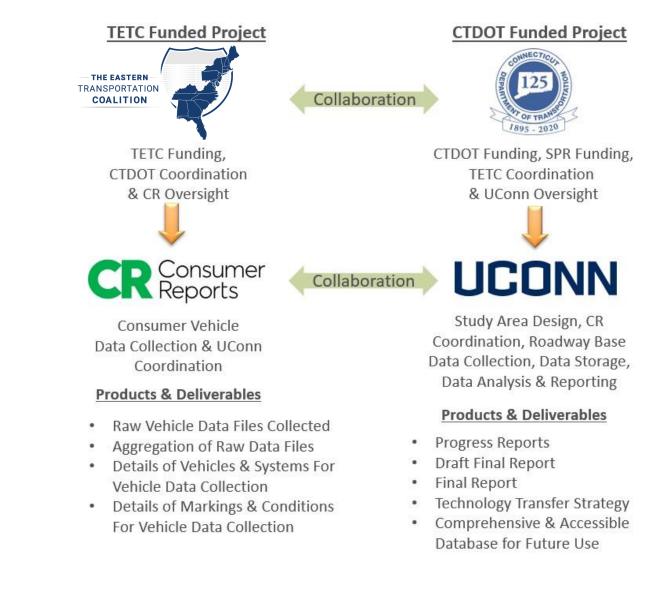
Study Area

- Evaluate the effect of pavement marking characteristics such as color, retroreflectivity, and lane marking width on machine vision detection
- Explore the machine vision lane marking detection accuracy under different lighting conditions and vehicle operational characteristics such as vehicle speed
- Explore the differences across different makes, models, and technologies used to detect lane marking while a vehicle is in operation under machine vision



Study Partners and Tasks

- ✓ Task 1: Literature Review
- ✓ Task 2: Study Design
- ✓ Task 3: Baseline Analysis of Study Area
- ✓ Task 4: Preliminary ADAS Base Data Collection
- ✓ Task 5: Full Scale Data Collection
- ✓ Task 6: Process and Archive Field Testing Data
- ✓ Task 7: Analyze Field Testing Data & Final Report



Study Design

- Old vs. New
 - Run Vehicles Pre & Post Line Stripe Improvement
- Day and Night
- □ 6 inch VS 4 inch
- Epoxy VS Water-based and Wet Reflective

Camera 4





- Laserlux® G7 Mobile Retroreflectometer
- Data Items: Retroreflectivity, Width, Color, Contrast

4-Camera setup

Racelogic Video VBOX Pro 20Hz VBVD10P 580TVL Camera NTSC

Assembly

Data Collection

- Site identification for pavement marking improvement
- Pre-construction pavement marking characteristics data collection
- CR vehicle base ground truth data collection

Pre-Construction

Construction Season

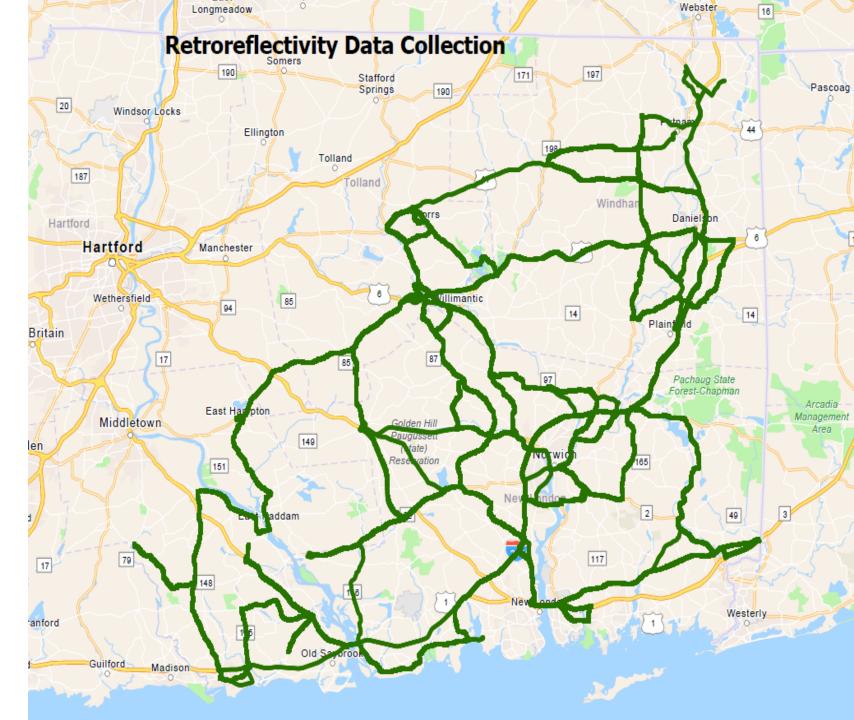
- Temporary paint on roadway
- Temporary pavement marking characteristics data collection
- CR vehicle temporary paint ground thuth data collection

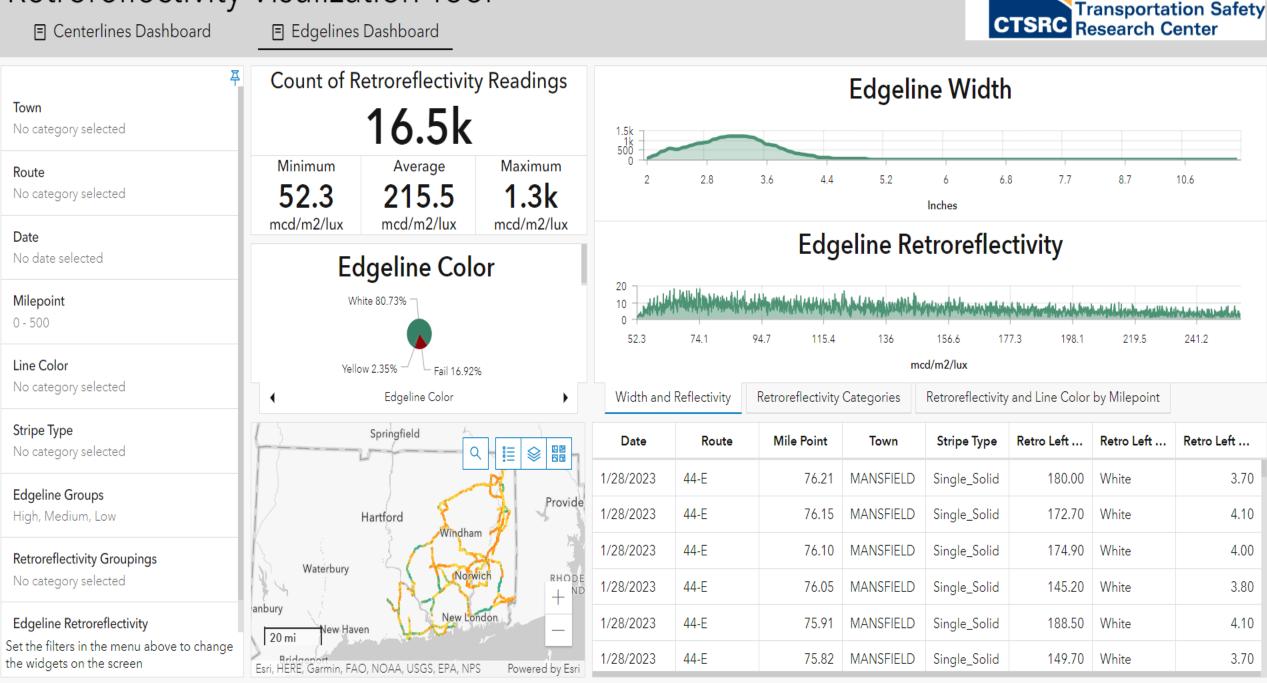
- Final paint on roadway
- Final pavement marking characteristics data collection
- CR vehicle ground truth data collection with final paint

Post-Construction

Retro Data Collection

- Centerline and Edge line data were collected separately
- Only for the rightmost lane
 - 1,245 miles of Centerline
 - 1,174 miles of Edge line



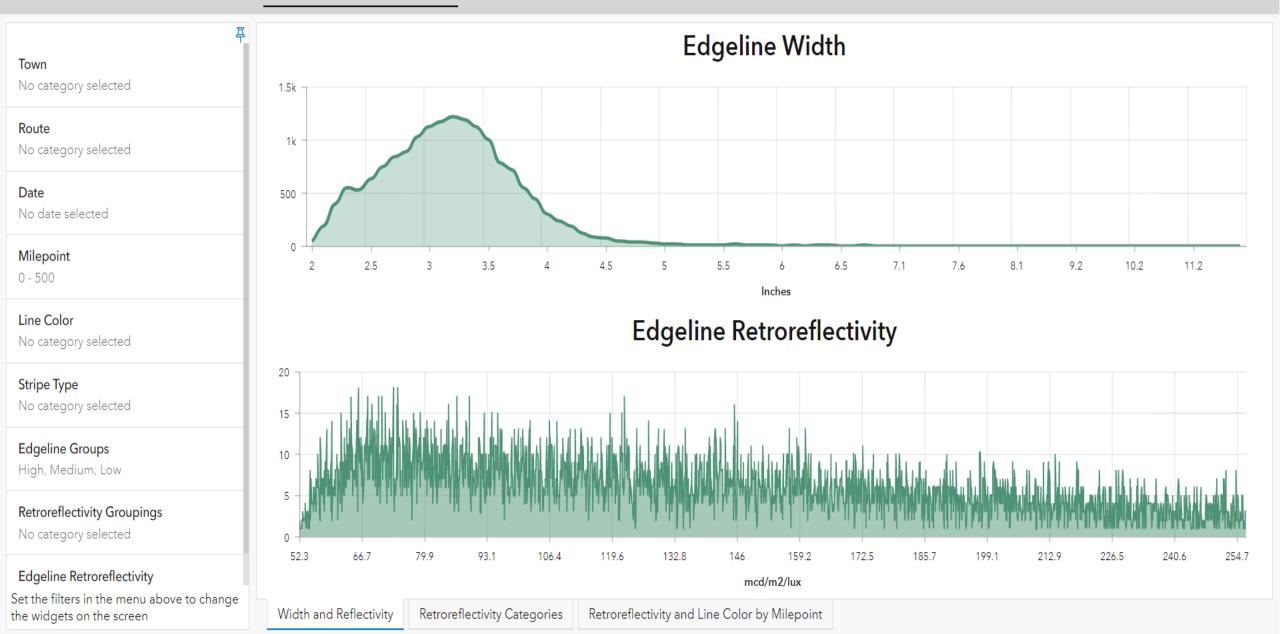


Connecticut



🗉 Edgelines Dashboard





E Centerlines Dashboard

Edgelines Dashboard







Route

11-N

Date

1/1/2022 - 1/1/2023

Milepoint

0 - 500

Line Color

No category selected

Stripe Type

No category selected

Edgeline Groups

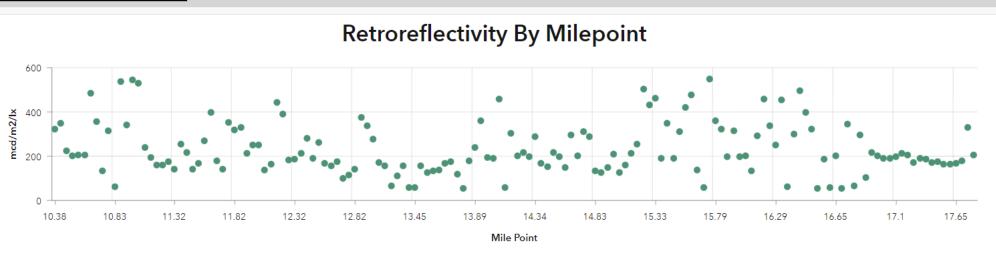
High, Medium, Low

Retroreflectivity Groupings

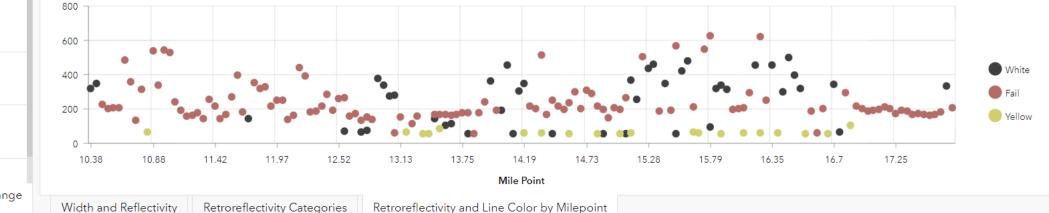
No category selected

Edgeline Retroreflectivity

Set the filters in the menu above to change the widgets on the screen







Pre-Construction – Rt. 11 North

E Centerlines Dashboard

Edgelines Dashboard







Route

Date

1/1/2023 - 3/1/2023

Milepoint

0 - 500

Line Color

No category selected

Stripe Type

No category selected

Edgeline Groups

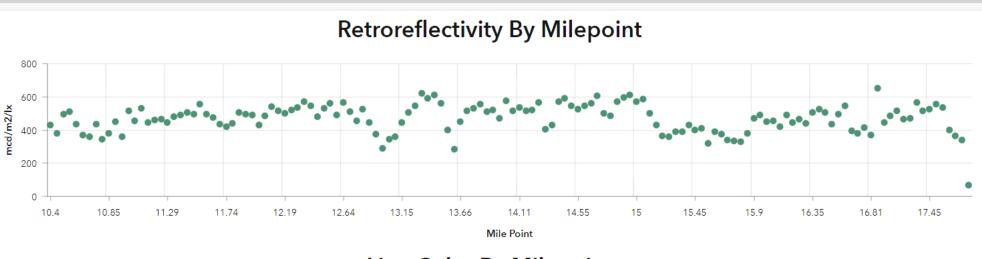
High, Medium, Low

Retroreflectivity Groupings

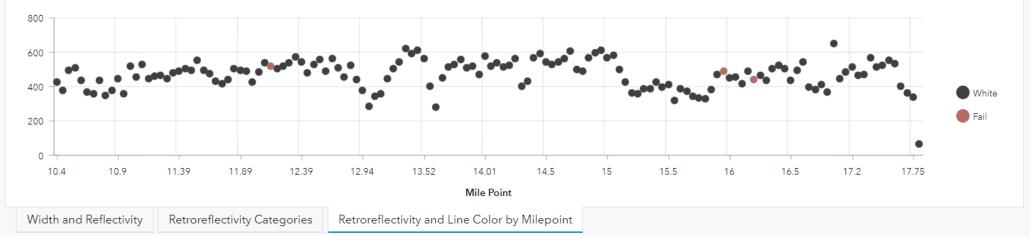
No category selected

Edgeline Retroreflectivity

Set the filters in the menu above to change the widgets on the screen



Line Color By Milepoint



Post Construction – Rt. 11 North

Study Vehicles



- Variety of Machine Vision Vendors "Under The Hood"
- 8 Vehicles: Different Makes and Models
 - Half are the "Most Common" Vehicles on the Market Today with This Technology onboard.
- Tesla & Super Cruise Not Included

Designation	Model Year	Description	Drivetrain	ADAS Detection Feature
Vehicle 1	2022	Sedan	FWD	Lane Keeping Assist System (LKAS)
Vehicle 2	2021	SUV	AWD	Lane Keep Assist (LKA)
Vehicle 3	2020	SUV	4WD	Lane Keep Assist (LKA)
Vehicle 4	2022	SUV	4x4	Active Lane Management System (ALMS)
Vehicle 5	2022	Crew Cab, Truck	4x4	Lane Tracing Assist (LTA)
Vehicle 6	2022	Crew Cab, Truck	AWD	Lane Keeping System (LKS)
Vehicle 7	2022	SUV	AWD	Lane Keeping Assist
Vehicle 8	2022	Minivan	FWD	Lane Keeping Assist & Lane following Assist.





Variation in Dashboard Indications



- Each system is different
- Indication types varies significantly



Excel Data File with GPS VBOX: A data logger that links coordinates videos with GPS coordinates Vertical_v/AviFileInd/AviSyncTir dgps_stati ComboG Distance ElapsedTir Combined LateralAcc LongitudinalAcceleration Satellite Time Latitude Longitude Velocity 05:43.4 41°0047.7:71°0055.0 5.212 11.74 44.25 1.037 -1 1.00E+00 5.65E-02 0.001 0 0.131 -0.055 0.119 0 05:43.4 41*0047.7.71*0055.0 5.422 12.77 44.24 1.037 -1 1.00E+00 8.85E-02 0.075 -0.055 0.119 0.05 0.131 ow Lap Time 7 Mithole Bession (0:31.55 05:43.5 41°0047.7.71°0055.0 5.516 12.28 44.23 1.166 -1 1.00E+00 7.07E-02 0.151 0.1 0.06 0.027 0.053 05:43.5 41°0047.7 71°0055.0 5.527 11.36 44.22 1.426 166 1.00E+00 3.90E-02 0.228 0.15 0.051 0.05 0.006 05:43.6 41°0047.7.71°0055.0 5.794 11.93 44.22 1.296 200 1.00E+00 9.49E-02 0.307 0.2 0.155 -0.033 0.151 05:43.6 41°0047.7 71°0055.0 5.746 13.14 44.22 1.166 266 1.00E+00 3.68E-02 0.387 -0.069 0.25 0.074 -0.027 05:43.7 41°0047.7 71°0055.0 6.047 13.56 44.21 1.166 300 1.00E+00 1.04E-01 0.469 0.3 0.172 -0.025 0.171 0 05:43.7 41°0047.7 71°0055.0 6.144 12.75 44.2 1.426 367 1.00E+00 7.87E-02 0.553 0.35 0.074 0.049 0.055 05:43.7 41°0047.7 71°0055.0 6.232 14.08 44.2 1.296 400 1.00E+00 6.71E-02 0.639 0.4 0.096 -0.082 0.05 05:43.8 41°0047.7 71°0055.0 6.369 13.75 44.18 1.555 467 1.00E+00 7.16E-02 0.727 0.45 0.08 0.021 0.078 05:43.9 41°0047.7 71°0055.0 6.507 14.11 44.18 1.555 500 1.00E+00 7.57E-02 0.816 0.5 0.082 -0.023 0.078 05:43.9 41°0047.7 71°0055.0 6.686 15.48 567 1.00E+00 9.28E-02 0.908 44.18 1.426 0.55 0.136 -0.091 0.101 05:44.0 41°0047.7 71°0055.0 7.039 15.45 44.17 1.555 600 1.00E+00 1.46E-01 1.003 0.6 0.2 0.002 0.2 05-44.0.41°0047.7.71°0055.0 7.036 17.57 44.16 1.814 -0.147 667 1.00E+00 8.56E-02 1.101 0.65 0.147 -0.002 05:44.1 41°0047.7 71°0055.0 7.196 700 1.00E+00 9.11E-02 0.7 17.83 44.15 1.814 1.2 0.093 -0.018 0.091 05:44.1 41°0047.7 71°0055.0 7.326 19.04 44.14 1.944 767 1.00E+00 9.27E-02 1.3 0.75 0.114 -0.088 0.074 05-44.2 41°0047.7 71°0055.0 7.842 20.06 44.13 2.074 800 1.00E+00 1.93E-01 1.406 0.8 0.303 -0.079 0.292 05:44.2 41°0047.7 71°0055.0 8.032 20.76 44.13 1.944 867 1.00E+00 1.57E-01 1.516 0.85 0.121 -0.056 0.108 05:44.3 41°0047.7 71°0055.0 8.258 22.13 44.11 2.203 900 1.00E+00 1.53E-01 1.629 0.9 0.17 -0.112 0.128 0 05:44.3 41°0047.7.71°0055.0 8.477 23.15 44.11 2.203 967 1.00E+00 1.49E-01 1.745 0.95 0.151 -0.085 0.124 05:44.3 41°0047.7 71°0055.0 8.75 25.06 44.1 2.333 1001 1.00E+00 1.68E-01 1.865 1 0.226 -0.165 0.155 05:44.4 41°0047.7 71°0055.0 9.066 26.23 44.09 2.333 1067 1.00E+00 1.86E-01 1.989 0.207 -0.105 0.179 1.05 05:44.4 41°0047.7 71°0055.0 9.201 28.72 44.09 2.074 1101 1.00E+00 1.69E-01 2.116 1.1 0.239 -0.227 0.076 9.552 29.91 44.08 2.203 1167 1.00E+00 1.98E-01 2.246 05:44.5 41°0047.7 71°0055.0 1.15 0.228 -0.112 0.199 05:44.6 41°0047.7.71°0055.0 9.925 31.23 44.08 1.944 1201 1.00E+00 2.21E-01 2.381 1.2 0.248 -0.13 0.211 05:44.6 41°0047.7 71°0055.0 9.92 32.47 44.08 1.685 1267 1.00E+00 1.51E-01 2.519 1.25 0.122 -0.122 -0.003 05:44.7 41°0047.7.71°0055.0 10.241 33.61 44.07 1.685 2.659 1301 1.00E+00 1.82E-01 1.3 0.215 -0.115 0.182 44.07 1.555 05:44.7 41°0047.7 71°0055.0 10.519 33.76 1368 1.00E+00 1.77E-01 2.803 1.35 0.158 -0.016 0.157 05:44.8 41°0047.7 71°0055.0 10.57 34.88 44.06 1.555 1401 1.00E+00 1.35E-01 2.95 1.4 0.121 -0.117 0.029 τ. 🔪 📑 δ 🗮 😡 w Channel VBCx0006 (Current) Whole Session Speed (km/h) 66.36 LustAcc (g) -0.085 05:44.8 41°0047.7 71°0055.0 10.623 34.24 1468 1.00E+00 9.04E-02 44.06 1.685 3.097 1.45 0.074 0.067 0.03 05:44.9 41°0047.7.71°0055.0 10.902 34.39 44.06 1.685 1501 1.00E+00 1.23E-01 3.246 1.5 0.159 -0.016 0.158 0 05:44.9 41°0047.7 71°0055.0 11.23 34.55 44.06 1.555 1568 1.00E+00 1.55E-01 3.4 1.55 0.187 -0.018 0.186 05:45.0 41°0047.7 71°0055.0 11.588 35.57 44.05 1.814 1601 1.00E+00 1.86E-01 3.558 1.6 0.234 -0.117 0.203 05:45.0 41°0047.7 71°0055.0 11.583 37.03 44.07 1.555 1668 1.00E+00 1.20E-01 3.719 0.167 -0.167 -0.003 1.65 05:45.1 41°0047.7 71°0055.0 11.927 38.23 44.07 1.426 1701 1.00E+00 1.70E-01 3.883 1.7 0.241 -0.142 0.195 05:45.1 41°0047.7 71°0055.0 12.27 39.3 44.07 1.296 1768 1.00E+00 1.96E-01 4.051 1.75 0.234 -0.13 0.194 05:45.1 41°0047.7:71°0055.0 12.408 40.88 44.07 1.296 1801 1.00E+00 1.72E-01 4.222 1.8 0.209 -0.194 0.078 05:45.2 41°0047.7 71°0055.0 12.769 41.57 44.06 1.555 1868 1.00E+00 1.99E-01 4.397 1.85 0.222 -0.087 0.205 05:45.3 41°0047.7 71°0055.0 13.186 43.21 44.06 1.814 4.577 1935 1.00E+00 2.41E-01 1.9 0.319 -0.214 0.236 05:45.3 41°0047.7 71°0055.0 13.58 44.98 44.06 1.814 1968 1.00E+00 2.62E-01 4.763 1.95 0.326 -0.238 0.223 Tistance (m) 0.0 0 05:45.4 41°0047.7 71°0055.0 13.927 46.31 44.06 1.685 2002 1.00E+00 2.60E-01 4.954 2 0.269 -0.183 0.197 05:45.4 41°0047.7 71°0055.0 14.376 47.84 44.06 1.814 2068 1.00E+00 2.86E-01 5.15 2.05 0.335 -0.217 0.254 05:45.5 41°0047.7:71°0055.0 14.664 48.95 44.05 1.944 2102 1.00E+00 2.59E-01 5.352 2.1 0.229 -0.161 0.163 0 05:45.5 41°0047.7.71°0055.0 14.95 50.52 44.05 2.074 2168 1.00E+00 2.55E-01 5.558 2.15 0.283 -0.232 0.162 2202 1.00E+00 2.47E-01 5.768 05:45.6 41°0047.7.71°0055.0 15.258 51.39 44.05 2.074 2.2 0.218 -0.131 0.174 **Data Analysis Process:** Review the dashboard video from the VBOX file and add a flag in the Excel Data file when lane marking is not detected

Data Issues

- Real-world data collection can be affected by several factors
 - Traffic factors, Contextual factors, Equipment used, # of sites
- Collected ground truth data was affected by
 - Video quality (glare, camera position)
 - GPS error
 - File naming scheme
 - Variation is dashboard indications across vehicles
 - Painting schedule

Satellites	BrakeTrigg DGP	S	Rtk	WavFile	Time	Latitude	Longitude	Velocity	Heading	Height	Vertical_v A
0	0	0	0	0	15:23.5	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.6	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.7	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.7	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.8	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.8	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.9	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:23.9	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.0	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.0	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.0	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.1	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.1	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.2	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.2	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.3	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.3	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.4	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.4	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.5	0°0000.00	0°0000.00	0	0	0	0
0	0	0	0	0	15:24.6	0°0000.00	0°0000.00	0	0	0	0
< >	VBO	x000)3, Whol	e Sessio	n	+					

Last Marking Date

RouteId	Town(s)	Project Type	BGN MILES	END MILES	LOG LENGTH	Termini	Date of Last Permanent Marking
6-E	Brooklyn/ Killingly	VIP	109.43	110.9	1.47	.06 Miles West of East jct. Brickyard Rd. to Start o/p Quinebaug River	11/20/2022
11-N	SALEM	Ultra-Thin	10.38	17.8	7.42	SR-82 to SR-2	11/7/2023
11-S	SALEM	Ultra-Thin	10.38	17.8	7.42	SR-82 to SR-2	11/7/2023
12-N	Plainfield	VIP	23.44	26.29	2.85	Griswold TL to OP Mill Brook	6/5/2023
12-N	Killingly/ Putnam	VIP	39.81	44.65	4.84	Town Farm Road #2 to Heritage Road	12/1/2022
12-N	Plainfield	VIP	27.91	32.13	4.22	N. Jct Rte 14A Academy Hill Road to Rte 205 n/b Wauregan Road	11/28/2022
14-E	Plainfield	VIP	13.46	16.99	3.53	W. JCT RT. 14A TO 12	5/31/2023
82-E	SALEM	Chip-Seal	17.6	20.2	2.6	.03 MI E/O END ROUNDABOUT (NEW LONDON RD) TO RTE 354 (EB) (OLD COLCHESTER RD)	8/18/2022
163-N	MONTVILLE/ BOZRAH	VIP	7.46	12.56	5.1	RT. 82 TO SR-2 BOZRAH ST. EXT.	6/8/2023
164-N	Preston/ Griswold	VIP	0	7.83	7.83	Rte 2 Norwich Westerly Road to end of Route 164	12/9/2022
165-E	Norwich/ Preston	VIP	0	5.16	5.16	Rt 2 to Rt 164	6/7/2023
2A-E	Montville/ Preston	VIP	4.37	7.05	2.68	BGN OP I-395 TO RTE 12 (INCLUDE RAMPS)	9/30/2022
2А-Е	Preston	VIP	7.35	9.91	2.56	Route 12 Military Hwy to End of Route 2A	9/29/2022
607-Е	Killingly	VIP	0	2.54	2.54	RT. 12 TO SOUTH FRONTAGE RD.	11/21/2022
6-E	KILLINGLY	Trad. Epoxy	111.32	113.62	2.3	RT. 12 TO SR. 607 (Brickyard Rd)	Done by Another Contractor
12-N	NORWICH/ LISBON	Trad. Epoxy	15.2	19.55	4.35	RT. 97 TO NB. ACCESS TO I395	Done by Another Conractor

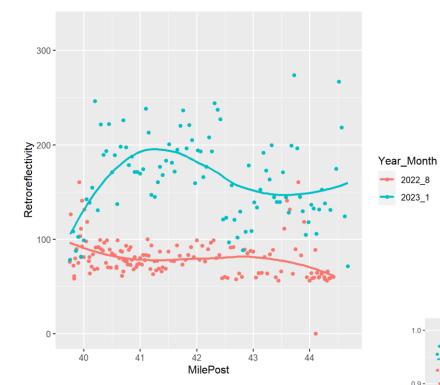
		2022										
Vehicle ID	Day/Night	June	July	Aug		Sep	0	ct Dec		Jan		
Vahiala 1	Day	157.95	0 0		350).07	0		228.3	0		
Vehicle 1	Night	57.32	0	0		282		0 298		0		
Vehicle 2	Day	76.3	0	142.67	0		1000.63*		123.85	0		
venicie 2	Night	56.9	0	134.13		0	146.3		0	0		
Vahiala 2	Day	93.2	0	0 0		0		0	0	0		
Vehicle 3	Night	46.33	0	0		0	1715.33	3*	0	109.92		
Valiala 4	Day	135.33	0	0		0	0		0	0		
Vehicle 4	Night	138.25	0	0	0		279.95		0	0		
Vahiala 5	Day	52.13	0	165.88	319	9.22		0	0	210.58		
Vehicle 5	Night	63.25	0	144.93	311	1.53		0	0	226.73		
Vahiala	Day	0	0	0	159.08		0		0	1095.68*		
Vehicle 6	Night	0 0		0	0		0		224.2			
Valiala 7	Day	81.35	0	0		0	276.4	13	0	0		
Vehicle 7	Night	0	57.98	0	0		129.2	27		0		
Vabiala 9	Day	0 246.5 141		141.22	150.4		138.4	42		217.93		
Vehicle 8	Night	0	156.72	131.85	148.65		121.3		0	235.3		
	0	51-100	101-15	0 15	1-200	2	01-250	~	251-300	>301		
Legend:		51-100	101-13			201-250		231-300		/ 501		

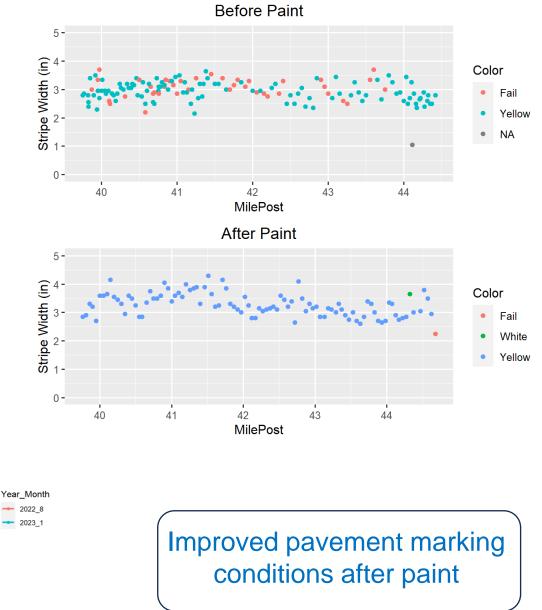
Note: Values with "*" exclude files that cannot be processed in the Circuit Tool

Data Distribution

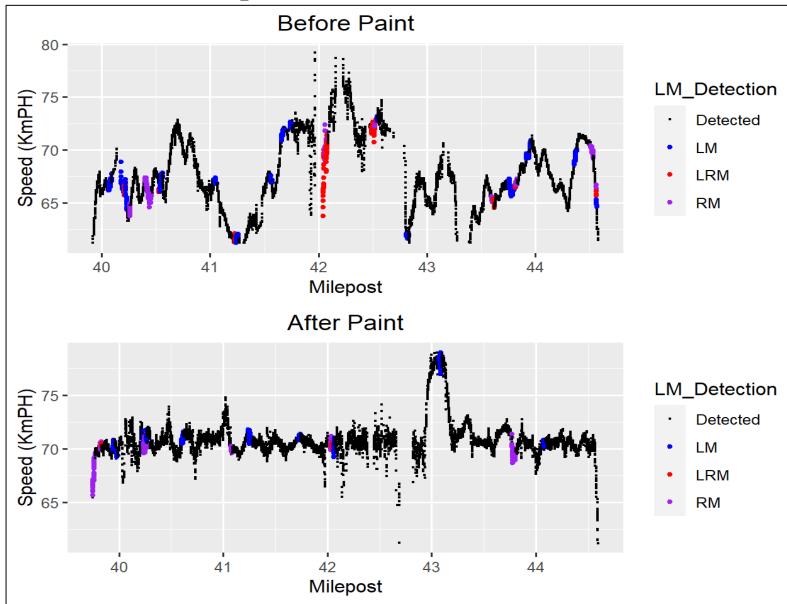
SiteID	Period	_ Day/	Vehicle 1				Vehicle 2				Vehicle 3				Vehicle 4				Vehicle 5			
		Night	Date	Count	%- LM	%-RM	Date	Count	%-LM	%-RM	Date	Count	%-LM	%-RM	Date	Count	%- LM	%-RM	Date	Count	%-LM	%-RM
	Defense	Day					6/21/22	4940	10.12	9.92	6/7/22	5697	51.61	46.16	6/9/22	5743	3.83	3.83				
	Before	Night	6/29/22	5482	0	0	6/23/22	5376	0	0					6/9/22	5556	3.78	4.14	6/20/22	5671	16.40	8.29
12N_VIP	During	Day	9/14/22	2974	4.37	0													9/24/22	2119	8.97	0
1128		Night	9/15/22	3607	0	0	10/20/22	3577	0	0									9/23/22	1841	0	0
	After	Day	12/19/22	5451	0	0	12/5/22	5297	12.27	10.38	1/24/23	3640	0	0					1/11/23	5623	0	27.39
	Alter	Night	12/8/22	5946	0	0													1/17/23	5312	0	5.84
	Before	Day	6/24/22	6410	14.20	2.96	6/21/22	6235	114.03	123.66	6/7/22	6719	215.36	134.39	6/9/22	6863	2.04	3.93				
	Belore	Night	6/29/22	6362	0	0	6/23/22	6897	81.77	88.59					6/9/22	6628	4.07	3.92	6/20/22	6772	90.52	61.72
12N_VIP 1201	During	Day	9/14/22	3869	0	0													9/24/22	3992	0	0
		Night	9/15/22	4903	0	15.91	10/20/22	7065	0	9.34									9/23/22	6866	10.34	9.18
	After	Day	12/19/22	6860	0	0	12/5/22	3386	48.73	48.73									1/17/23	7403	68.62	110.23
		Night	12/8/22	6628	0						1/24/23	668	28.44	28.44					1/11/23	7511	36.35	31.29
	Before	Day	6/24/22	9999	0	0	6/21/22	1842	13.57	14.66					6/9/22	10416	6.72	6.43	6/17/22	8179	15.53	14.55
		Night													6/9/22	10135	0	0.79	6/20/22	5691	2.81	5.62
164N_VIP	During	Day	9/30/22	8324	0		8/25/22	7898	0	0									9/27/22	9723	15.02	25.71
1209	During	Night	9/29/22	7612	0		8/25/22	10765	0	0									9/27/22	6844	7.89	60.78
	After	Day	12/19/22	11360	0						1/18/23	6858	122.34	125.40					1/11/23	10726	13.52	54.82
	1 III OI	Night	12/30/22	10888	0						1/24/23	6460	75.08	70.43					1/17/23	11382	10.28	8.43
		Day	6/2/22	6274	0	3.51	6/21/22	2784	93.39	100.57	6/6/22	3414	146.46	172.52	6/8/22	3217	43.83	43.83	6/17/22	2667	61.49	86.24
	Before	24)	6/24/22	3512	0	0													8/16/22	3448	160.67	67.00
	201010	Night									6/6/22	3599	135.87	134.76	6/8/22	3480	6.32	6.32	6/20/22	3281	84.43	68.27
2AE_VIP		Ĵ.																	8/16/22	3012	47.81	48.47
0930	During	Day	9/30/22	3182	0	3.46													9/27/22	3258	109.88	113.26
		Night	9/29/22	3593	0.83	7.51	8/25/22	3509	31.92	31.92									9/27/22	2781	0	69.76
	After	Day	12/19/22	3311	21.44	2.42					1/18/23	613	107.67	83.20					1/17/23	3104	39.63	134.99
	11101	Night	12/30/22	3515	68.28	3.13					1/24/23	3299	210.97	138.22					1/11/23	3329	126.76	64.88

Data Analysis





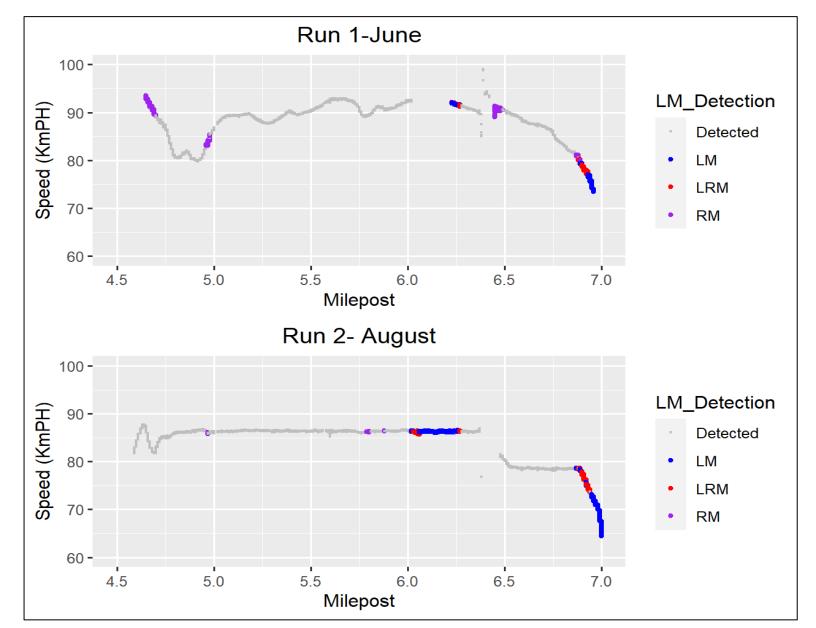
Data Analysis: Before vs After



Takeaways

- Failed to detect lane markings
 - In both high and low speed
 - In after condition with improved markings

Data Analysis: Comparing Same Condition



Takeaways

- Not consistent detection on the same site using the same vehicle
- Failed to detect lane markings in both high and low speed

Special Events



Changes in Lane Marking Types

Raised Curb



Wide Lanes



Conclusions

- No apparent relationship between pavement marking characteristics and pavement marking detection capability of ADAS.
 - ADAS detected lane markings with retroreflectivity <100 mcd/m2/lux.
 - ADAS was able to detect lane stripe width \approx 3 inches.
 - Similar trend was observed with pavement marking color and contrast.
- The "None Detected" events were not associated with vehicle speed.
- Special scenarios were identified where ADAS failed to detect lane markings
 Changes in lane marking type and color
 - Wide lane
 - \circ Object on the road

Recommendations

- Lessons learned on real-world ADAS data collection
- Design future studies
 - Design defined data collection procedure
 - Data accuracy check
 - Multiple runs on the same location with varying speeds, and pavement marking characteristics
- Careful study site selection
- Define an appropriate data archiving procedure





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Q&A and Discussion



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THANK YOU

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